

Technical Comments

Comment on "Relative Variation of Rocket Vehicle Specific Impulse and Structural Weight Fraction for Constant Burnout Velocity"

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Nomenclature

e = Napierian logarithmic base, 2.718
 g_0 = mass conversion factor
 I_{sp} = specific impulse
 s = ratio of structural weight to initial gross weight
 l = ratio of payload weight to initial gross weight
 V_{bo} = vehicle flight velocity at end of burning
 V_e = exhaust velocity
 V_o = flight velocity
 η_p = propulsive efficiency

IN Ref 1, which is concerned with optimum rocket flight performance, a discussion of the relative influence of changes in propulsion system design or propellant capability is presented. An equation, (3-23b) of Ref 1, which expresses the ratio $\Delta I_{sp}/\Delta s$, is derived for conditions of constant burnout velocity and zero- g flight in vacuum. The final equation is in error, as are the curves of Fig 3-9, p 3-15 of Ref 1. The correct results are derived by writing the equation for burnout velocity

$$V_{bo} = g_0 I_{sp} \ln[1/(s+l)] \quad (1)$$

Then

$$\frac{dV_{bo}}{ds} = -g_0 I_{sp} \left(\frac{1}{s+l} \right) + g_0 \ln \left(\frac{1}{s+l} \right) \frac{dI_{sp}}{ds} \quad (2)$$

For constant V_{bo} , $dV_{bo}/ds = 0$. Then Eq (2) gives

$$\frac{dI_{sp}}{ds} = I_{sp} \left(\frac{1}{s+l} \right) \left\{ \frac{1}{\ln[1/(s+l)]} \right\} \quad (3)$$

or

$$\frac{\Delta I_{sp}}{\Delta s} = -I_{sp} \left[\frac{1}{(s+l) \ln(s+l)} \right] \quad (4)$$

Equation (4) is the corrected version of Eq (3-23b) of Ref 1. The variation of $\Delta I_{sp}/\Delta s$ with $s+l$ is presented in Fig 1 in the manner of Fig 3-9 of Ref 1. As the rocket vehicle becomes more structurally efficient, i.e., small values of $s+l$, the conclusion of Ref 1 is correct: large increases in specific impulse can be offset by small fractional increases in structural weight. However, as the vehicle becomes structurally inefficient (high values of $s+l$) the curves of constant specific impulse exhibit a positive increasing slope rather than being asymptotic to the $s+l$ axis¹ as $s+l$ approaches 1.0. Thus, the same conclusion is true for high values of the structural weight fraction.

The minimum points on the curves obviously occur at the value of structural fraction which will allow the maximum

variation in structural weight fraction for the least required change in specific impulse. Equation (3) may be differentiated to give

$$\frac{d^2 I_{sp}}{ds^2} = -I_{sp} \left[\frac{-[\ln(s+l) + 1]}{[(s+l) \ln(s+l)]^2} \right] \quad (5)$$

At the minimum point $d^2 I_{sp}/ds^2 = 0$ and, thus

$$s+l = 1/e = 0.368 \quad (6)$$

for minimum $\Delta I_{sp}/\Delta s$. Substitution of $s+l = 1/e$ in Eq (1) gives

$$V_{bo} = g_0 I_{sp} \ln e = g_0 I_{sp} \quad (7)$$

The burnout velocity is then equal to the theoretical nozzle exit velocity ($V_{bo} = V_e = g_0 I_{sp}$).

It is interesting to note that the rocket propulsive efficiency η_p is a maximum at this condition since

$$\eta_p = \frac{2V_o/V_e}{1 + (V_o/V_e)^2} \quad (8)$$

and $\eta_p \rightarrow 1.00$ for $V_{bo} = V_e = V_o$. It is concluded that the maximum permissible variation in structural weight fraction with the minimum required change in propellant capability (I_{sp}) occurs at values of vehicle mass ratio in the neighborhood of $e = 2.718$, which is coincident with maximum propulsive efficiency.

References

- 1 Summerfield, M. and Seifert, H. S., "Flight performance of a rocket in straight line motion," *Space Technology*, edited

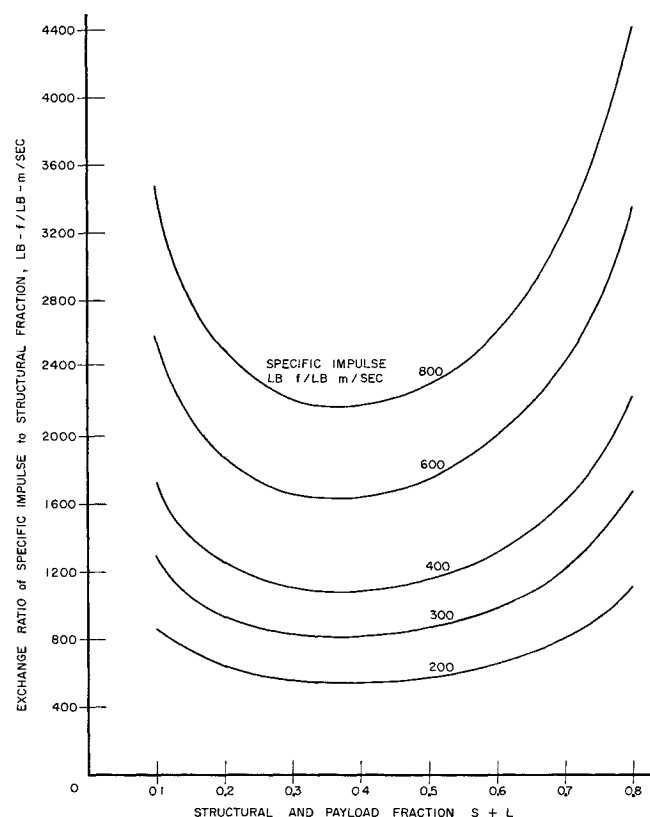


Fig 1 Exchange ratio curves for $\Delta I_{sp}/\Delta s$, zero- g vacuum flight

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by H. S. Seifert (John Wiley and Sons, Inc., New York, 1959), Chap. 3, pp. 3-14-3-15

² Sutton, G. P., *Rocket Propulsion Elements* (John Wiley and Sons, Inc., New York, 1956), 2nd ed., p. 19

Slip Flow and Hypersonic Boundary Layers

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The problem of the hypersonic similar laminar boundary layer is modified to include first order slip boundary conditions. It is observed that the inclusion of these new boundary conditions result in no change in the energy transfer to the wall from the no-slip values, implying that slip effects alone are not adequate to explain the appearance of the heat transfer "plateaus" observed near the leading edge of a sharp flat plate in hypersonic flow. In addition, it is shown how the inclusion of slip boundary condition as the only higher order effect results in complete disagreement with observed pressure measurements for the cold-wall case.

IN a recent note, Talbot¹ suggests a criterion for slip flow near the sharp leading edge of a flat plate in hypersonic flow. It is significant that the parameter suggested by Talbot as a suitable correlating parameter for heat transfer and induced pressure experiments can be interpreted both as the ratio of the mean free path behind the shock wave to the boundary layer thickness, as well as the ratio of the leading edge shock thickness to the distance from the leading edge. Although Talbot's correlating parameter is not really the appropriate one which arises from the inclusion of slip boundary conditions to the traditional strong hypersonic viscous interaction problem, it can, of course, be related to that parameter. The author has included first-order slip boundary conditions in the calculation of heat transfer for that case and has arrived at the not unexpected conclusion that there is no effect of hypersonic laminar heat transfer of the inclusion of slip velocity and temperature jump boundary conditions. This result, which was obtained earlier by Maslen² for a zero-pressure gradient no-slip flow is here extended to the class of hypersonic similar solutions characterized by $u = \text{const}$, $p \sim x^n$. These solutions, which were tabulated by Dewey,³ include the conventional no-slip strong interaction problem where $p \sim x^{-1/2}$. Our negative result is restricted only to the heat transfer to the wall. Induced pressure and skin friction, on the other hand, in general will exhibit a first-order slip effect. Thus the possibility is raised that additional higher order effects besides slip will be necessary to account for the observed pressure and heat transfer "plateaus".

At the present time, it is not clear just how a systematic approach to the solution of the Navier-Stokes equation should proceed for this geometry, and there is even the possibility that coupling between the viscous boundary layer and the shock structure may not be very well represented by the Navier-Stokes equation. It is felt that it is inappropriate to attribute to slip flow and rarefaction effects which may well be within the scope of the Navier-Stokes equations.

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It is quite apparent from our results that slip flow alone is incapable of reducing the energy transfer to the wall from the usual strong interaction result. Perhaps the success of Talbot's parameter in correlating both induced pressure and heat transfer measurements hinges on its dual significance as an estimator of the effects of shock-structure viscous flow field coupling, as well as an estimator of slip effects.

Analysis

Consider a perfect gas, constant Prandtl number, and arbitrary viscosity-temperature dependence. The flow external to the boundary layer is presumed to be hypersonic, corresponding to the limit $U_\delta^2/2H\delta \rightarrow 1$. The notation of Hayes and Probstein⁴ is used throughout.

The form of the first-order slip boundary conditions in the η, ξ variables suggests that the appropriate expansion parameter for first-order slip effects is $\epsilon \equiv \lambda_w \rho_w U_\delta / (2\xi_0)^{1/2}$. For the hypersonic no-slip similar flows corresponding to $U_\delta = \text{const}$, $p_0 \sim x^n$, this parameter ϵ varies as $x^{-(n+1/2)}$. Consider a first-order expansion in ϵ of f, g, p, ξ , and $\rho\mu/\rho_w\mu_w$:

$$\left. \begin{aligned} f &= f_0(\eta) + \epsilon f_1(\eta) \\ g &= g_0(\eta) + \epsilon g_1(\eta) \\ p &= p_0[1 + \epsilon p_1] \\ \xi &= \xi_0[1 + 2\epsilon p_1] \\ \rho\mu/\rho_w\mu_w &\equiv (\mu/T)(T_w/\mu_w) \equiv N \\ N &= N_0 + \epsilon \left(\frac{T_w}{g_w} \frac{dN}{dT} \right)_{T=T_0} (g_1 - 2f_1 f_0') \end{aligned} \right\} \quad (1)$$

If the effect of the self-induced pressure gradient is to be calculated, then p_1 will be determined by a suitable relationship between the displacement thickness and the pressure. Otherwise it may be set identically equal to zero. In the analysis of the heat transfer, which will be given below, it is quite apparent that its magnitude does not enter into consideration at all. It does, however, enter into the momentum equation as a coefficient of an inhomogeneous term and consequently will be involved in the skin friction and in the solution for f_1 and g_1 .

The first-order boundary layer equations with appropriate boundary conditions become

$$\begin{aligned} \frac{\partial}{\partial \eta} \left\{ N_0 f_1'' + \frac{T_w}{g_w} \left(\frac{dN}{dT} \right)_{T=T_0} (g_1 - 2f_0' f_1') f_0'' \right\} + f_1 f_0'' + \\ f_0 f_1'' + \beta_0 [g_1 - 2f_0' f_1'] + \beta_1 \beta_0 (g_0 - f_0')^2 = \\ \left[\beta_0 \left(\frac{h\delta_0}{H\delta} \right) - 1 \right] [f_1 f_0' - f_1 f_0''] \quad (2a) \end{aligned}$$

$$\begin{aligned} \frac{1}{Pr} \frac{\partial}{\partial \eta} \left\{ N_0 g_1' + \frac{T_w}{g_w} \frac{dN_0}{dT} (g_1 - 2f_0' f_1') g_0' \right\} + f_0 g_1' + f_1 g_0' + \\ 2 \frac{\partial}{\partial \eta} \left\{ N_0 \left(1 - \frac{1}{Pr} \right) (f_1 f_0'' + f_0' f_1'') \right\} + \\ 2 \frac{\partial}{\partial \eta} \left\{ \frac{T_w}{g_w} \left(\frac{dN_0}{dT} \right)_{T=T_0} (g_1 - 2f_0' f_1') \left(1 - \frac{1}{Pr} \right) (f_0' f_0'') \right\} = \\ \left[\beta_0 \left(\frac{h\delta_0}{H\delta} \right) - 1 \right] [g_1 f_0' - f_1 g_0'] \quad (2b) \end{aligned}$$

The boundary conditions are $f_1'(0) = a_v f_0''(0)$, $g_1(0) = a_T g_0'$, where a is a velocity slip coefficient, a_T is a temperature jump coefficient, $f_1(0) = 0$, $f_1'(\infty) \rightarrow 1$, $g_1(\infty) \rightarrow 0$. Note that

$$\frac{2dN_0 U_\infty H\delta}{d\ln \xi} \equiv \beta_0 (1 + \epsilon \beta_1) = \frac{\gamma - 1}{\gamma} \frac{n}{n - 1} \left(1 + \epsilon \frac{3}{2} p_1 \right) \quad (3)$$